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SCHOOL OF BUSINESS
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Mathematics in economics

Lecture 5

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Extremes of a function of two real variables

Local vs global extremes.

Bounded vs unbounded extremes.

Necessary condition for the extreme:

$$\frac{\partial^2}{\partial x^2} \quad \frac{\partial^2}{\partial y^2}$$

A point satisfying equalities above is called a stationary (critical) point. However, this condition is not sufficient

Extremes of a function of two real variables

In a critical point can be maximum, minimum or an inflection point. To decide which situation occurs, we use the second derivatives and a matrix called *hessian*:

$$H_f(x,y) = \begin{bmatrix} f''_{xx} & f''_{xy} \\ f''_{xy} & f''_{yy} \end{bmatrix}$$

Then we use Sylvester's theorem.

Extremes of a function of two real variables

We denote: $D_1 = \begin{vmatrix} f''_{xx} & f''_{xy} \\ f''_{xy} & f''_{yy} \end{vmatrix}$ and $D_2 = H_f(C)$. Then:

If $D_2 > 0$, then we have an extreme. Moreover,
 If $D_1 > 0$, we have a minimum, if $D_1 < 0$, we have a maximum.

If $D_2 < 0$, we have an inflection point.

If $D_2 = 0$, we cannot decide.

Extremes of a function of two real variables - Problem 1

Find extremes of the function $f(x,y) = x^2 - y^2$.

Solution:

We start with the first derivatives:

$$\frac{\partial f}{\partial x} = 2x \quad \frac{\partial f}{\partial y} = -2y$$

Both derivatives must be 0, which yields the critical point $C [0,0]$.

Extremes of a function of two real variables - Problem 1 – cont.

Now we compute all second derivatives and hessian:

$$\frac{\partial^2 f}{\partial x^2}, \quad \frac{\partial^2 f}{\partial y^2}, \quad \frac{\partial^2 f}{\partial x \partial y}, \quad \frac{\partial^2 f}{\partial y \partial x}$$

$$H_f(x,y) = \begin{bmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial^2 f}{\partial x \partial y} \\ \frac{\partial^2 f}{\partial y \partial x} & \frac{\partial^2 f}{\partial y^2} \end{bmatrix}$$

We substitute point C into hessian: $Hf(0,0) = \begin{bmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial^2 f}{\partial x \partial y} \\ \frac{\partial^2 f}{\partial y \partial x} & \frac{\partial^2 f}{\partial y^2} \end{bmatrix}$.

Because $D_2 < 0$, the point C is an inflection point.

Extremes of a function of two real variables - Problem 2

Find extremes of the function $f(x,y) = x^2 - y^2 + 1$.

Solution:

We start with the first derivatives:

$$\frac{\partial f}{\partial x} = 2x - 2y = 0 \quad \frac{\partial f}{\partial y} = -2y + 2x = 0$$

Both derivatives must be 0, which yields the critical point $C [1/2, 1/2]$.

Extremes of a function of two real variables - Problem 2 – cont.

Now we compute all second derivatives and hessian:

$$\frac{\partial^2 f}{\partial x^2} = -2 \quad \frac{\partial^2 f}{\partial y^2} = -2 \quad \frac{\partial^2 f}{\partial x \partial y} = 0$$

$$H_f(x,y) = \begin{bmatrix} -2 & 0 \\ 0 & -2 \end{bmatrix}$$

Substituting point C into hessian yields the same result.

Because $D_2 < 0$, the point C is an inflection point.

Extremes of a function of two real variables - Problem 3

Find extremes of the function $f(x,y) = x^4 + y^4$.

Solution:

We start with the first derivatives:

$$\frac{\partial f}{\partial x} = 4x^3 = 0 \qquad \frac{\partial f}{\partial y} = 4y^3 = 0$$

Both derivatives must be 0, which yields the critical point $C [0,0]$.

Extremes of a function of two real variables - Problem 3 – cont.

Now we compute all second derivatives and hessian:

$$\frac{\partial^2 f}{\partial x^2} = 4x^2 \quad \frac{\partial^2 f}{\partial x \partial y} = 0$$

$$H_f(x,y) = \begin{bmatrix} 4x^2 & 0 \\ 0 & 0 \end{bmatrix} \quad H_f(C) = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

Because $D_2 = 0$, We cannot decide the nature of C.
But how do we know it is certainly a minimum?

Problem 4

Find the maximum of the revenue function:

$$TR(Q, Q) = 100Q - 2Q^2 + 100Q - 2Q^2$$

Solution:

We start with the first derivatives:

$$\frac{\partial TR}{\partial Q} = 100 - 4Q \quad \frac{\partial TR}{\partial Q} = 100 - 4Q$$

Both derivatives must be 0, which yields the critical point C [12.5, 2].

Problem 4 – cont.

Now we compute all second derivatives and hessian:

$$H_f(x,y) = \begin{bmatrix} & \\ & \end{bmatrix} \quad H_f(C) = \begin{bmatrix} & \\ & \end{bmatrix}$$

Because $D_2 > 0$, we have an extreme.

Because $D_1 < 0$, we have a maximum.

Problems to solve – 1 (Assignment 7)

Find extremes of the following functions:

$$f(x, y) = x^2 + y^2 + 2x - 4y$$

$$f(x, y) = x^2 - y^2 + 2x - 4y$$

$$f(x, y) = 2xy - 3x^2 - 2y^2 + 10$$

$$f(x, y) = y - \frac{y^3}{3} + \ln x - \frac{1}{x}$$

$$f(x, y) =$$

Indefinite integral

Integration is a reverse procedure to differentiation.

Notation: \int + \int

Legend:

\int Integration sign
 $f(x)$ Integrated function
 C Integration constant

Indefinite integral - cont

Indefinite integral is a linear operator:

$$\int (af + bg) = a \int f + b \int g$$

We compute integrals with the use of formulas above, and with the use of the table of elementary integrals, see the next slide.

Indefinite integral – elementary integrals

$f(x)$	$\int f(x)dx$
0	C
1	$x + C$
x^n	$\frac{x^{n+1}}{n+1} + C$
e^x	$e^x + C$
$\frac{1}{x}$	$\ln x + C$
$\frac{1}{ax+b}$	$\frac{1}{a} \ln ax+b + C$
a^x	$\frac{a^x}{\ln a} + C$

Indefinite integral – elementary integrals

$\sin x$	$-\cos x + C$
$\cos x$	$\sin x + C$
$\frac{1}{\cos^2 x}$	$\operatorname{tg} x + C$
$-\frac{1}{\sin^2 x}$	$\operatorname{cot} g x + C$
$\frac{1}{1+x^2}$	$\operatorname{arctg} x + C$
$\frac{1}{a^2+x^2}$	$\frac{1}{a} \operatorname{arctg} \frac{x}{a} + C$
$\frac{1}{\sqrt{1-x^2}}$	$\operatorname{arcsin} x + C$
$-\frac{1}{\sqrt{1-x^2}}$	$\operatorname{arccos} x + C$
$\frac{1}{\sqrt{1\pm x^2}}$	$\ln \left x + \sqrt{1\pm x^2} \right + C$

Indefinite integral - examples

$$\int \left(\frac{x^3}{3} + \frac{x^4}{4} + x^3 + x^2 + 1 \right) dx = \frac{x^4}{4} + \frac{x^3}{3} + x^2 + x + C$$

Indefinite integral - examples

$$\begin{aligned}
 & \int \left(x^2 + \frac{1}{x} \right) dx \\
 & \int \left(x^2 + \frac{1}{x} - 3x + 2x^3 \right) dx \\
 & \int x^2 dx + \int \frac{1}{x} dx + \int 1 dx + \int x^2 dx - \int 3x dx + \int 2x^3 dx \\
 & \int x^2 dx + \int \frac{1}{x} dx + \int 1 dx + \int x^2 dx - \frac{3}{2}x^2 + \frac{2}{4}x^4 + C \\
 & \int x^2 dx + \int \frac{1}{x} dx + \int 1 dx + \frac{1}{3}x^3 - \frac{3}{2}x^2 + \frac{1}{2}x^4 + C
 \end{aligned}$$

Indefinite integral – integration methods

For more complicated integration we use suitable integration methods:

- Method per partes
- Partial fractions
- Substitutions

All these methods will be demonstrated on examples.

Indefinite integral – rational functions

By a rational function we mean the function of the form:

$$\frac{P(x)}{Q(x)}$$

where $P(x)$ and $Q(x)$ are polynomials.

In the first step we find the roots x_i of the denominator in order to rearrange the denominator into a product.

$$\frac{P(x)}{Q(x)} = \dots + \frac{A(x)}{(x - x_i)^k} + \dots$$

Indefinite integral – rational functions – cont.

Then, the situation splits into three possible cases:

1. All roots of a denominator are single. Then we obtain the following partial fractions:

$$\frac{H(x)}{Q(x)} = \frac{H_1(x)}{\Delta} + \frac{H_2(x)}{\Delta} + \dots + \frac{H_n(x)}{\Delta} + \frac{R}{\Delta} + \frac{K}{\Delta}$$

2. Some root, for example x_1 , is of order higher than 1:

$$\frac{H(x)}{Q(x)} = \frac{H_1(x)}{\Delta} + \frac{H_2(x)}{\Delta^2} + \dots + \frac{H_n(x)}{\Delta^n} + \frac{R}{\Delta} + \frac{K}{\Delta}$$

Indefinite integral – rational functions – cont.

3. A denominator or its part given as a quadratic polynomial has no roots:

$$\frac{H(x)}{Q(x)} = \frac{H_1(x)}{Q_1(x)} + \frac{H_2(x)}{Q_2(x)} + \frac{H_3(x)}{Q_3(x)} + \dots + \frac{H_n(x)}{Q_n(x)} + \frac{R(x)}{Q(x)}$$

Coefficients in numerators are unknown and must be computed by clearing a denominator and solving a subsequent equation.

Integration of rational functions – Problem 1

Solve: $\int \frac{3x+1}{x^2-1} dx$.

Solution: The rational function is of case 1, with roots -2 and 1. Therefore, we obtain the following division into partial fractions:

$$\frac{3x+1}{x^2-1} = \frac{A}{x+1} + \frac{B}{x-1}$$

Now we clear the denominator:

$$3x+1 = A(x-1) + B(x+1)$$

And we get two equations: $\begin{cases} 3 = A + B \\ -1 = -A + B \end{cases}$

Integration of rational functions – Problem 1-cont.

Solving the equation yields: $A_{-} = \frac{1}{2}$.

Hence: $\frac{3x+1}{x^2+1} = \frac{1}{2(x+1)} + \frac{5}{2(x-1)}$

Now, we can integrate:

$$\int \frac{3x+1}{x^2+1} dx = \frac{1}{2} \int \frac{1}{x+1} dx + \frac{5}{2} \int \frac{1}{x-1} dx = \frac{1}{2} \ln|x+1| + \frac{5}{2} \ln|x-1| + C$$

We will continue in Lecture 6.

Thank you for your attention!